Building recursive data structures in Haskell

Duncan Coutts 4/12/03

Infinite Values

- Haskell allows us to build 'infinite values' with finite representation
- For example the prelude function repeat returns an infinite list of the same element

repeat :: a -> [a] repeat x = x : x : x : ...

Representation

 recursive structures can be represented using pointers



Representation

• In traditional imperative languages we would explicitly use pointers

```
struct List {
    void *head;
    List *tail;
}
List * repeat(void *x) {
    List *xs = new List;
    xs->head = x;
    xs->tail = xs; /* close the loop */
    return xs;
}
```

Haskell version using let

• In Haskell we don't have mutable references but we do have lazy evaluation and recursive let

```
repeat :: a -> [a]
repeat x = let xs = x:xs
in xs
```

That's nice but how do we build more complicated structures?

•As a first example of building more complex cyclic structures we'll look at doubly linked lists



- The data type data List a = Node a (List a) (List a) | Nil
- Values of this type will not persist well, we will not be able to build them incrementally.
- We'll have to build them all in one go

```
mkList :: [a] -> List a
mkList [] = Nil
mkList (x:xs) = ???
```

• Some special cases

```
mkList :: [a] -> List a
mkList [] = Nil
mkList [x] = Node a Nil Nil
mkList [x1, x2] = let node1 = Node x1 Nil node2
node2 = Node x2 node1 Nil
in node1
mkList [x1, x2, x3] = let node1 = Node x1 Nil node2
node2 = Node x2 node1 node3
node3 = Node x3 node2 Nil
in node1
```

• For the general case we add an extra argument prev which is the previous node

mkList xs = mkList' xs Nil



node	link
a	3
b	0
C	3
d	2
e	2

- Next we'll look at graphs
- For starters we'll consider directed graphs where each node has exactly one outgoing edge

- The data type data Graph a = GNode a (Graph a)
- We want a function that builds a Graph from the table of nodes with explicit integer links

```
mkGraph :: [(a, Int)] -> Graph a
```



- Last time we built the structure by tracing a path through it.
- With the graph, the pattern of links is not linear or predictable.
- What recursive value can we name?

Let $x = \ldots x \ldots$

- We can name the table!
- We can build all the links 'simultaniously' by using a collection

```
mkGraph :: [(a, Int)] -> Graph a
mkGraph table = table' ! 0
where table' = listArray (0, length table - 1) $
map (\(x, n) -> GNode x (table' ! n)) table
```

This example uses a Haskell array, but any collection implementation that is lazy in its elements would do.

General Directed Graphs

• We can easily generalise the last example to general directed graphs

```
data GGraph a = GGNode a [GGraph a]
mkGGraph :: [(a, [Int])] -> GGraph a
mkGGraph table = table' ! 0
where table' = listArray (0, length table - 1) $
map (\(x, ns) ->
GGNode x (map (table' !) ns)) table
```

Advantages & Disadvantages

- Advantages of cyclic representations over representations with explicit links
 - No need to deal with node names
 - Faster structure traversal
- Disadvantages
 - Cannot "escape" structure
 - Cannot update structure incrementally

Thinking about sharing



• Once we've built one of these recursive values does traversing it really take constant space?



• Can we be sure that we're not allocating new nodes as we traverse the structure?

Thinking about sharing

• For example, earlier we defined

• Would this definition be 'the same'?

```
repeat' x = x:repeat' x
```

- We can easily prove them equal.
- So they're equal but not the same huh?

Thinking about sharing

- I don't know of a useful semantics that allows one to reason about sharing. Remember that Haskell is specified as non-strict, not lazy.
- We can hand wave and make assumptions about how our compiler implements things.
- We can experiment by looking inside the evaluation using Debug.trace