

Full Abstraction for Nominal General References

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Full Abstraction for Nominal General References – Overview

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We will be talking about:

- Nominal Sets (Gabbay, Pitts)
- A functional higher-order language with nominal general references (Pitts, Stark, NT), the $\nu\rho$ -calculus
- Nominal Games (Abramsky, Ghica, Murawski, Ong, Stark, NT)

Nominal Sets [GP99, Pit03]

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A *nominal set* X is a set equipped with an action from $\text{PERM}(N)$,

$$_ \circ _ : \text{PERM}(N) \times X \rightarrow X \quad (\text{e.g. } \pi \circ x)$$

Moreover, all $x \in X$ have finite support $S(x)$,

$$S(x) \triangleq \{\alpha \in N \mid \text{for infinitely many } \beta. (\alpha \beta) \circ x \neq x\}$$

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N is a nominal set, and so is $N^\#$ –the set of *finite lists* of distinct names.

Constructions in Nominal Sets

- ↪ If X, Y nominal sets then $X \times Y$ a nominal set.
- ↪ If Y a nominal set, $X \subseteq Y$, X closed under permutations then X is a *nominal subset* of Y .
- ↪ $R \subseteq X \times Y$ is a *nominal relation* iff $xRy \iff (\pi \circ x)R(\pi \circ y)$.
- ↪ $f : X \rightarrow Y$ is a *nominal function* iff $f(\pi \circ x) = \pi \circ f(x)$.
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E.g., $S(-) : X \rightarrow \mathcal{P}_{\text{fin}}(\mathbf{N})$ is a nominal function.
- ↪ If $\alpha \in \mathbf{N}$ and $x \in X$ then define $S(\langle \alpha \rangle x) = S(x) \setminus \{\alpha\}$
 $\langle \alpha \rangle x \triangleq \{(\beta, y) \in \mathbf{N} \times X \mid (\beta = \alpha \vee \beta \# x) \wedge y = (\alpha \beta) \circ x\}$

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↪ If $x \in X$ and $\vec{\alpha} \in \mathbf{N}^\#$ then define

$$S([x]_{\vec{\alpha}}) = S(x) \cap S(\vec{\alpha})$$

$$[x]_{\vec{\alpha}} \triangleq \{y \in X \mid \exists \pi. \pi \circ \vec{\alpha} = \vec{\alpha} \wedge y = \pi \circ x\}$$

A Language with Nominal References

Use names for general references!

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$$\text{TY} \ni A, B ::= \overset{\text{commands}}{\mathbb{1}} \mid \overset{\text{naturals}}{\mathbb{N}} \mid \overset{\text{references}}{[A]} \mid \overset{\text{functions}}{A \rightarrow B} \mid \overset{\text{pairs}}{A \otimes B}$$

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We need to work in Nominal Sets over *a collection of sets of names*,

$$\mathbf{N} \triangleq \bigsqcup_{A \in \text{TY}} \mathbf{N}_A$$

$$\text{PERM}(\mathbf{N}) = \bigoplus_{A \in \text{TY}} \text{PERM}(\mathbf{N}_A)$$

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Let Nom_{TY} be the category of nominal sets (on \mathbb{N}) and nominal functions.

\rightsquigarrow we denote names by a^A, b^B, \dots or α, β, \dots ,
and finite lists of distinct names by $\vec{\alpha}, \vec{\beta}, \dots$

The $\nu\rho$ -calculus

The $\nu\rho$ -calculus is a functional calculus with nominal references.

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$$\mathbf{TE} \ni M, N ::= x \mid \lambda x.M \mid M N \quad \lambda\text{-term}$$
$$\mid \text{skip} \quad \text{return}$$
$$\mid \tilde{n} \mid \text{pred } M \mid \text{succ } N \quad \text{arithmetic}$$
$$\mid \text{if0 } M \text{ then } N_1 \text{ else } N_2 \quad \text{if_then_else}$$
$$\mid \langle M, N \rangle \mid \text{fst } M \mid \text{snd } N \quad \text{pair / projections}$$

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$\mid \alpha$	name, $\alpha = a^A \in \mathbf{N}_A$
$\mid \nu\alpha.M$	ν -abstraction
$\mid [M = N]$	name-equality test
$\mid M := N \mid !M$	update / dereferencing

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$$\mathbf{VA} \ni V, W ::= \tilde{n} \mid \text{skip} \mid \alpha \mid x \mid \lambda x.M \mid \langle V, W \rangle$$

The $\nu\rho$ -calculus: Typed Terms

Terms are typed in environments $(\Gamma, \vec{\alpha})$ consisting of:

- a set Γ of variable-type pairs
- *a list* $\vec{\alpha}$ of distinct names ($\vec{\alpha} \in \mathbf{N}^\#$)

$$\vec{\alpha} \mid \Gamma \vdash M : A$$

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$$\frac{}{\vec{\alpha} \mid \Gamma, x : A \vdash x : A}$$

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$$\frac{\vec{\alpha} \mid \Gamma \vdash M : B}{\vec{\alpha} \mid \Gamma \vdash \nu \alpha. M : B}$$

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$$\frac{\vec{\alpha} \mid \Gamma \vdash M : [A] \quad \vec{\alpha} \mid \Gamma \vdash N : A}{\vec{\alpha} \mid \Gamma \vdash M := N : \mathbb{1}}$$

The $\nu\rho$ -calculus: Reduction

The reduction calculus is defined in store environments S :

$$S ::= \epsilon \mid \alpha, S \mid \alpha :: V, S$$

with their domains being lists of distinct names.

$$\text{EQ} \frac{}{S \vDash [\alpha = \beta]} \longrightarrow S \vDash \tilde{n} \quad \begin{array}{l} n=1 \text{ if } \alpha \# \beta \\ n=0 \text{ if } \alpha = \beta \end{array}$$

$$\text{NEW} \frac{}{S \vDash \nu\alpha.M} \longrightarrow S, \beta \vDash (\alpha \beta) \circ M \quad \beta \# S$$

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The $\nu\rho$ -calculus: An Example

$M \triangleq \nu\alpha. \alpha := (\lambda x^{\mathbb{N}}, y^{\mathbb{N}}. \text{if0 } x \text{ then } y \text{ else } (!\alpha)(\text{pred } x)(\text{succ } y)); !\alpha$

– *What does it do?*

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$$\longrightarrow S, \beta :: V \vDash V \tilde{0} (m \tilde{+} n) \longrightarrow S, \beta :: V \vDash m \tilde{+} n$$

$\nu\rho$ -calculus : Observational Equivalence

The semantics yields the following notion of equivalence.

For typed terms $\vec{\alpha} \mid \Gamma \vdash M : A$ and $\vec{\alpha} \mid \Gamma \vdash N : A$,

$$\vec{\alpha} \mid \Gamma \vdash M \approx N \iff$$

$$\forall C[-] : \mathbb{N}. (\exists S'. \vdash C[M] \longrightarrow S' \vdash \tilde{0})$$

$$\implies (\exists S''. \vdash C[N] \longrightarrow S'' \vdash \tilde{0})$$

where $C[-]$ is a variable- and name-closing context.

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For example,

$$\nu\alpha.\nu\beta.\lambda f^{\mathbb{N}_A \rightarrow \mathbb{N}}. (\text{zero}(f\alpha) \iff \text{zero}(f\beta)) \not\approx \lambda f^{\mathbb{N}_A \rightarrow \mathbb{N}}. \tilde{0}$$

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e.g. $C \triangleq \nu\gamma. \gamma := \tilde{2}; [_] \lambda x. (\gamma := \text{pred}(!\gamma); !\gamma)$

The Adventure - Fully Abstract Semantics

The goal:

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The plan:

- Rectify nominal games of [AGM⁺04];
- Define a store monad in the category of nominal games
–solve a *domain equation*;
- Show soundness;
- Restrict games
–obtain *tidy strategies*;
- Show definability.

Nominal Games

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Nominal games were introduced in [AGM⁺04] in order to provide the first FA semantics for the ν -calculus. They modelled local state using *sets of names*, yet sets were incompatible with *determinacy* of strategies: the model was flawed.

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Nominal Games = CBV games of [HY99]

+ moves with state of [Ong02]

+ Nominal Sets *and strong support*

For X a nominal set, $x \in X$, x has strong support iff

$$\forall \pi. (\pi \circ x = x \iff \forall \alpha \in S(x). \pi(\alpha) = \alpha)$$

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- A nominal set M_A of moves with strong support;
- A nominal justification relation $\vdash_A \subseteq (M_A + \{\dagger\}) \times M_A$;
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↪ Answers may only justify Questions.

Basic Arenas, Prearenas

$$\begin{array}{lll} \boxed{1} & M_1 \triangleq \{*\} & \boxed{\mathbb{N}} & M_{\mathbb{N}} \triangleq \mathbb{N} & \boxed{N_A} & M_{N_A} \triangleq N_A \\ & \lambda_1(*) \triangleq PA & & \lambda_{\mathbb{N}}(m) \triangleq PA & & \lambda_{N_A}(m) \triangleq PA \\ & \vdash_1 \triangleq \{(\dagger, *)\} & & \vdash_{\mathbb{N}} \triangleq \{(\dagger, m)\} & & \vdash_{N_A} \triangleq \{(\dagger, m)\} \end{array}$$

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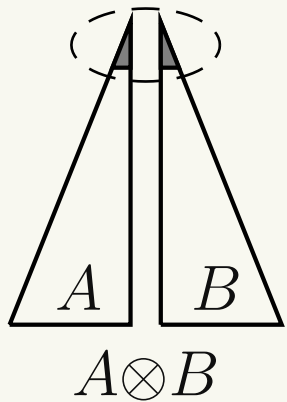
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A *prearena* is an arena with its initial moves labeled OQ .

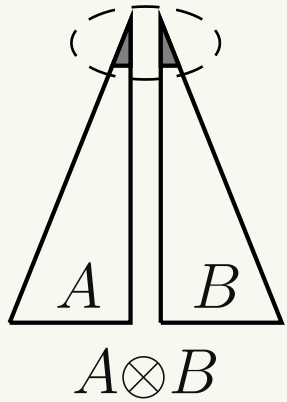
Arena Constructions

For nominal arenas A, B , define $A \otimes B$, A_{\perp} , $A \overset{\sim}{\Rightarrow} B$ and $A \Rightarrow B$:



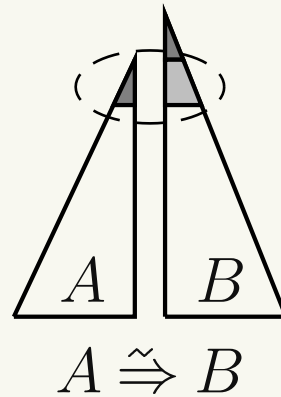
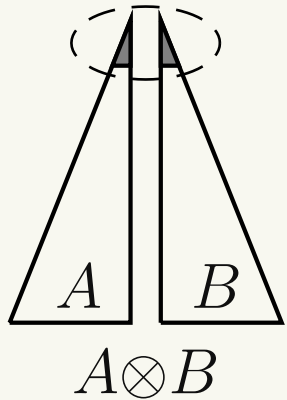
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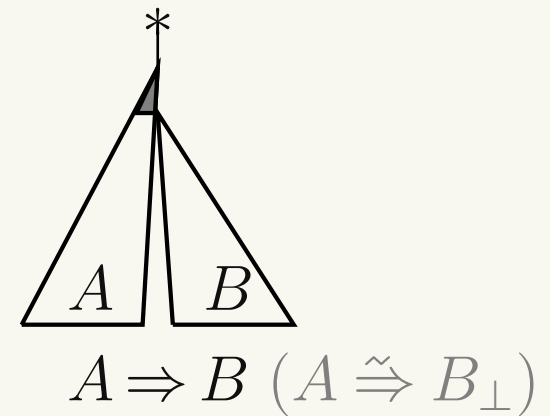
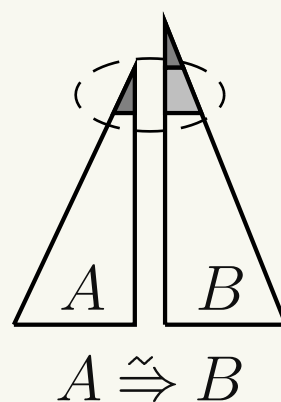
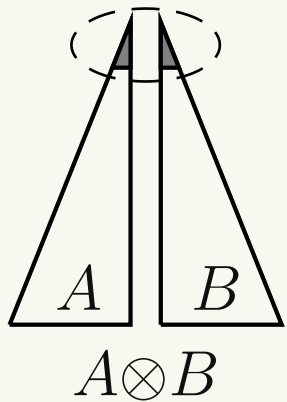
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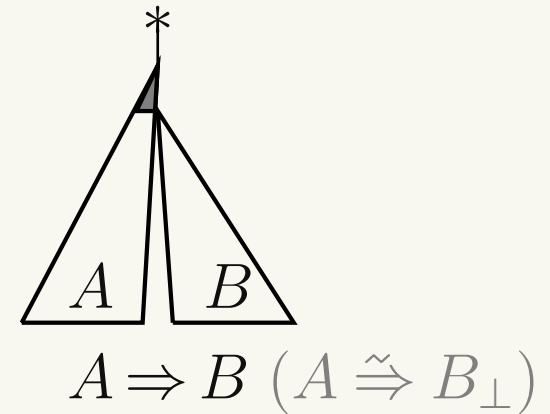
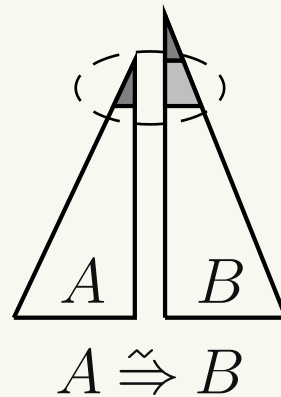
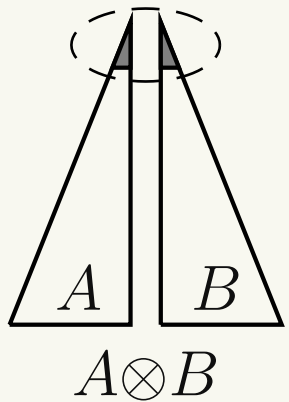
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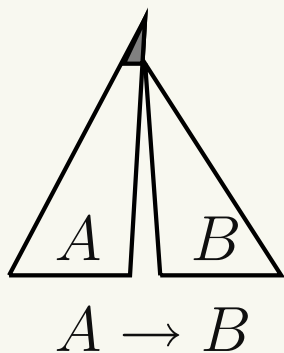


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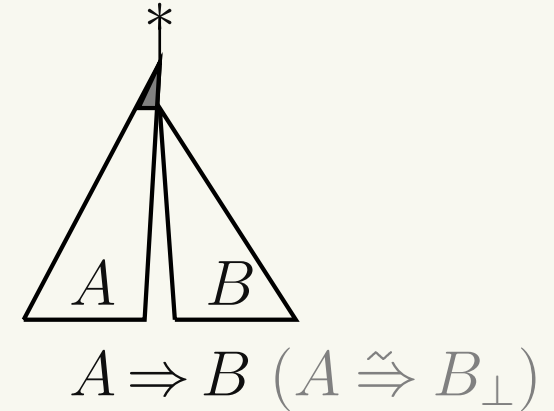
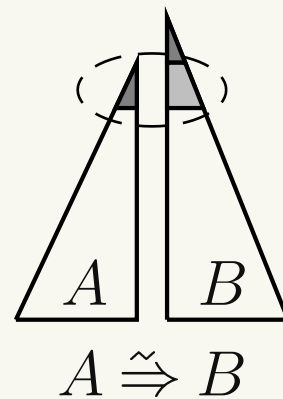
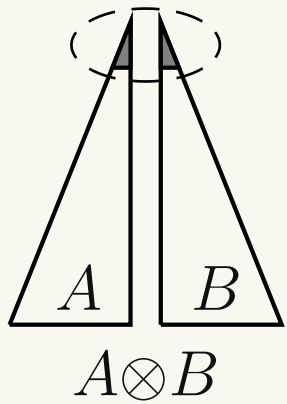


Also, the prearena $A \rightarrow B$:

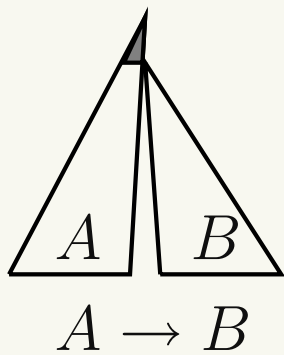


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Also, the prearena $A \rightarrow B$:



$$M_{A \rightarrow B} \triangleq M_A + M_B$$

$$\lambda_{A \rightarrow B} \triangleq [(i_A \mapsto OQ), m_A \mapsto \overline{\lambda_A}(m_A)], \lambda_B]$$

$$\vdash_{A \rightarrow B} \triangleq \{(\dagger, i_A), (i_A, i_B)\} \cup \{(m, n) \mid m \vdash_{A, B} n\}$$

Sequences of Moves

For a prearena A , a sequence s of moves from A is:

- A *justified sequence* of moves if:
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Visibility & Well-Bracketing

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Moreover, the *P-view*, $\lceil s \rceil$, of a justified sequence s is given by:

$$\lceil sx \rceil \triangleq \lceil s \rceil x \quad \text{if } x \text{ a P-move}$$

$$\lceil x \rceil \triangleq x \quad \text{if } x \text{ is initial}$$

$$\lceil sx \widehat{s'} y \rceil \triangleq \lceil s \rceil \widehat{x} y \quad \text{if } y \text{ an O-move justified by } x$$

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A *play* is a legal sequence of moves-with-names s satisfying:

- (NC1) P-moves may (only) add fresh names to the local state;
- (NC2) If a P-move x contains in its support a name α that is fresh for the previous P-view then α must appear in $\text{nlist}(x)$;
- (NC3) O-moves don't change the local state even if they contain fresh names in their supports.

An *$\vec{\alpha}$ -play* is a play with its first move having name-list $\vec{\alpha}$.

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A *play* is a legal sequence of moves-with-names s satisfying:

(NC1) If x a P-move in s preceded by y then $\text{nlist}(y) \leq \text{nlist}(x)$;
if $\alpha \notin \text{nlist}(x)$ and $\alpha \in \text{nlist}(y)$ then $\alpha \in s_{<x}$ (α introduced by P).

(NC2) If x a P-move, $\alpha \notin x$ and $\alpha \in \lceil s_{<x} \rceil$ then $\alpha \notin \text{nlist}(x)$.

(NC3) If y an O-move justified by z then $\text{nlist}(y) = \text{nlist}(z)$.

An $\vec{\alpha}$ -*play* is a play with its first move having name-list $\vec{\alpha}$.

Plays: Examples

$$N_A \longrightarrow N_A \Rightarrow N_A$$

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OQ

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$*\alpha$

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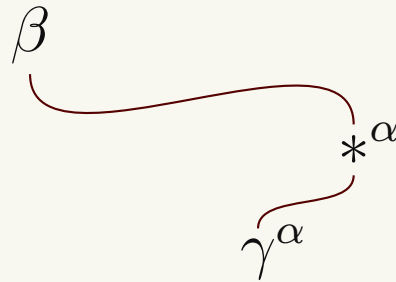
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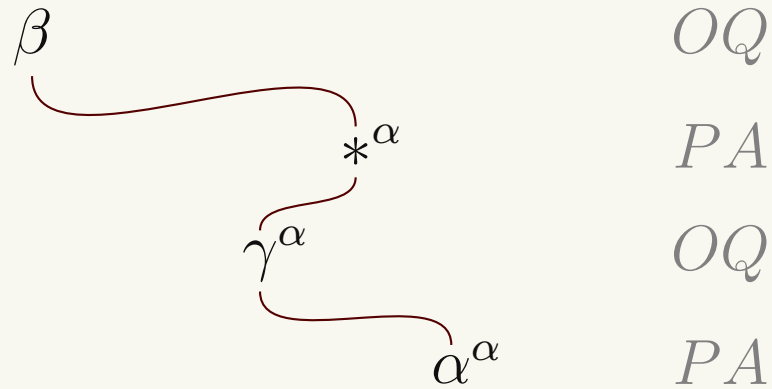
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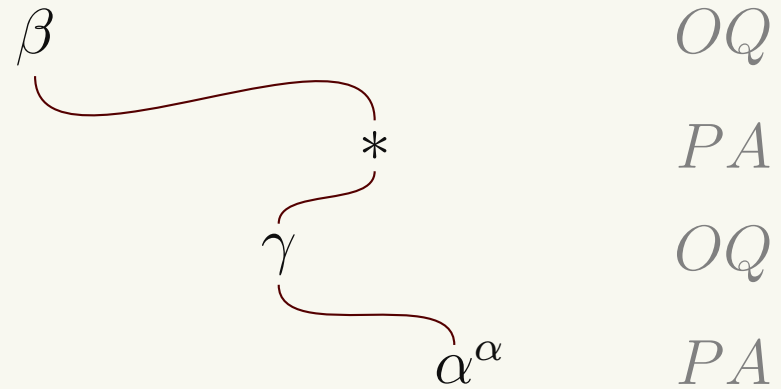
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Strategies

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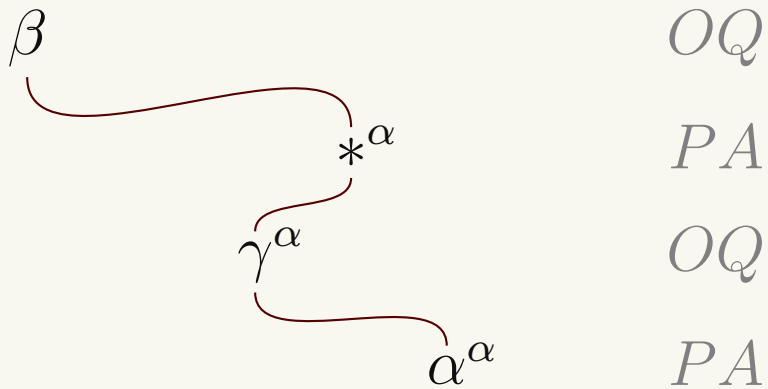
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An $\vec{\alpha}$ -strategy σ on $A \rightarrow B$ is written $\sigma : A \rightarrow B$.

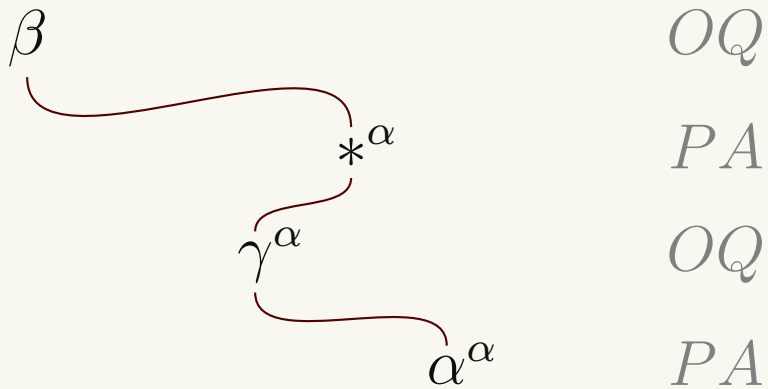
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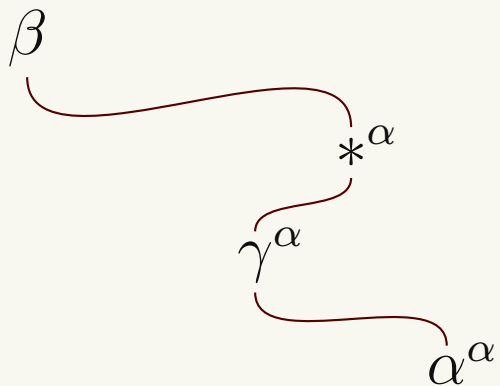
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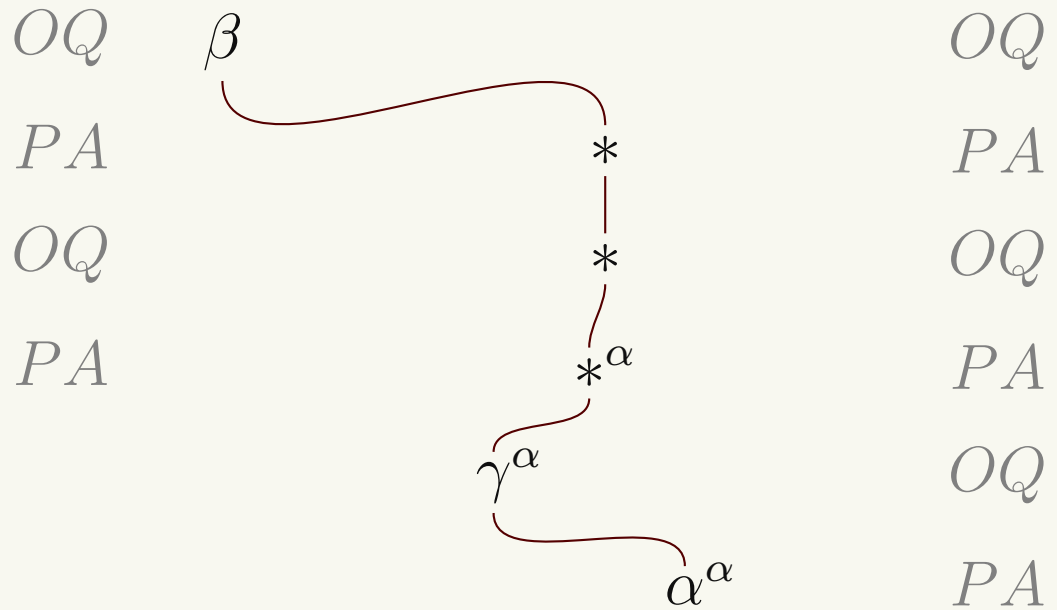
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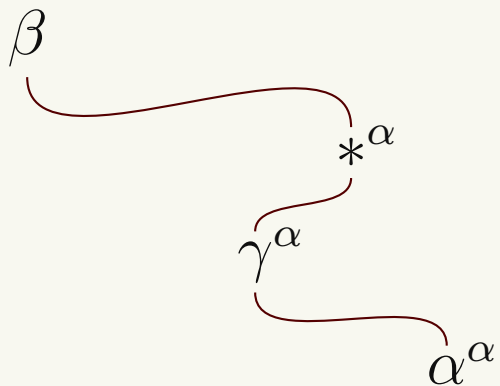
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$$N_A \longrightarrow (N_A \Rightarrow N_A)_\perp$$



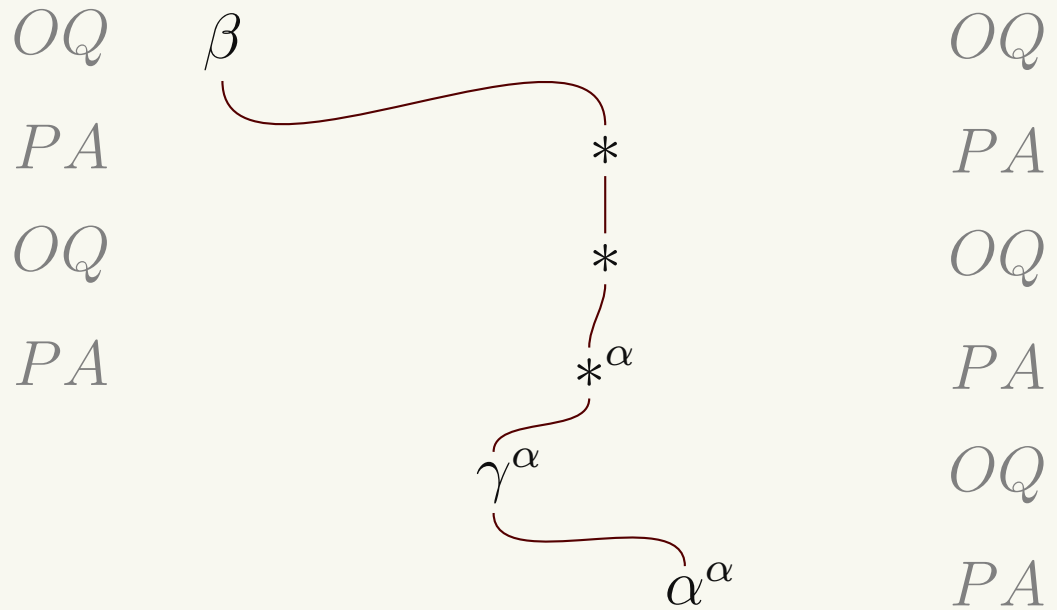
Strategies: Examples

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($\llbracket \mid x:[A] \vdash \nu\alpha.\lambda y.\alpha \rrbracket$)

The category $\mathcal{V}_t^{\vec{\alpha}}$

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Note: Our intention is to translate each typed term $\vec{\alpha} \mid \Gamma \vdash M : A$ to an arrow $[\Gamma] \rightarrow T[A]$ in $\mathcal{V}_t^{\vec{\alpha}}$.

\rightsquigarrow Accommodate *name-addition* and *name-abstraction*.

Properties of $\mathcal{V}_t^{\vec{\alpha}}$

$\mathcal{V}_t^{\vec{\alpha}}$ is a symmetric monoidal category under \otimes , and is partially closed in the following sense.

For any object B , for any object A and any *pointed object* C there exists a bijection

$$\Lambda_{A,C}^B : \mathcal{V}_t^{\vec{\alpha}}(A \otimes B, C) \xrightarrow{\cong} \mathcal{V}_t^{\vec{\alpha}}(A, B \rightrightarrows C)$$

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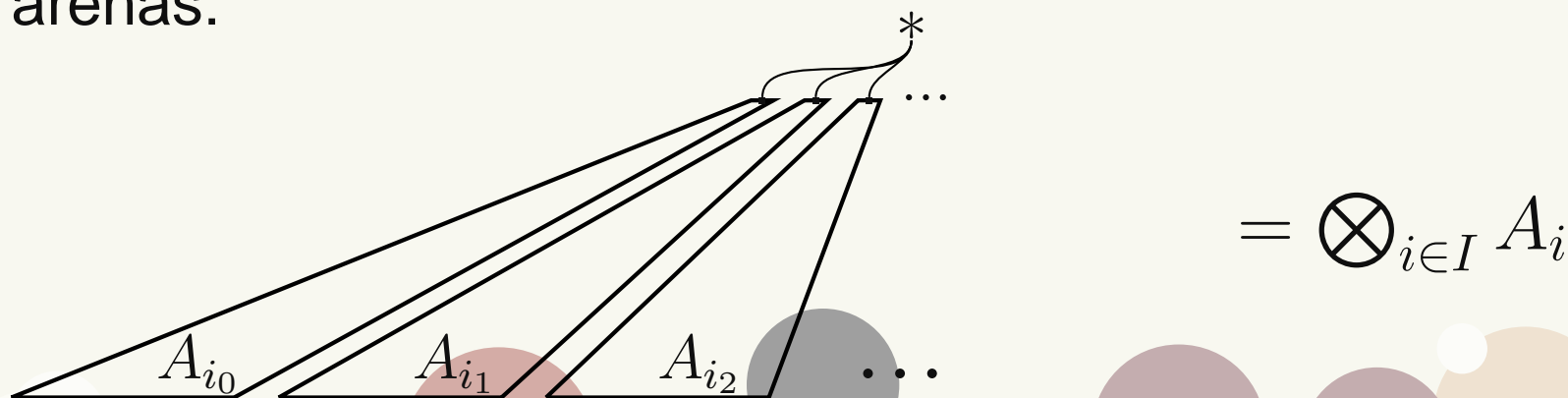
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We can also extend \otimes to an infinite tensor product of pointed arenas:



The Store Equation

We view general references as an effect and formulate a monadic semantics for $\nu\rho$. If types A are translated to $\llbracket A \rrbracket$ then we require:

$$\llbracket 1 \rrbracket = 1 \quad \llbracket \mathbb{N} \rrbracket = \mathbb{N} \quad \llbracket [A] \rrbracket = N_A \quad \llbracket A \otimes B \rrbracket = \llbracket A \rrbracket \otimes \llbracket B \rrbracket$$

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1. Use the categorical machinery of [SP82] for solving recursive domain equations, as adapted to games in [McC00].
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Having solved (SE) we obtain a strong monad (T, η, μ, τ) :

$$TA = \xi \Rightarrow (A \otimes \xi)$$

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The previous reasoning applies for all $\vec{\alpha}$, so we obtain a model

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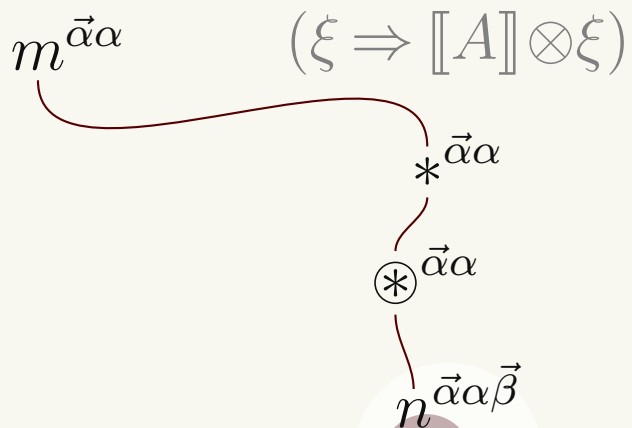
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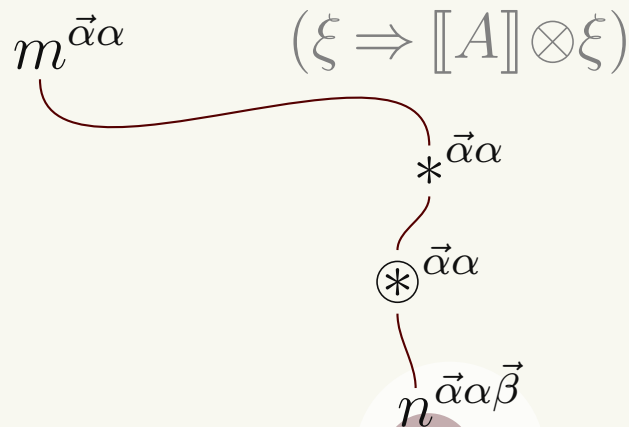
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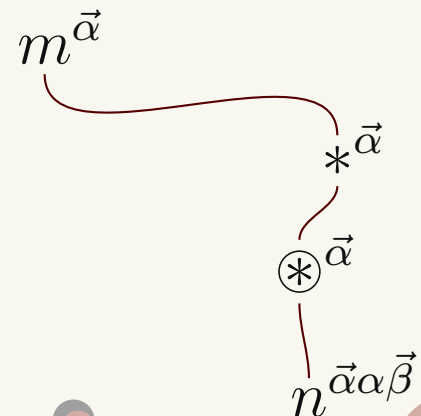
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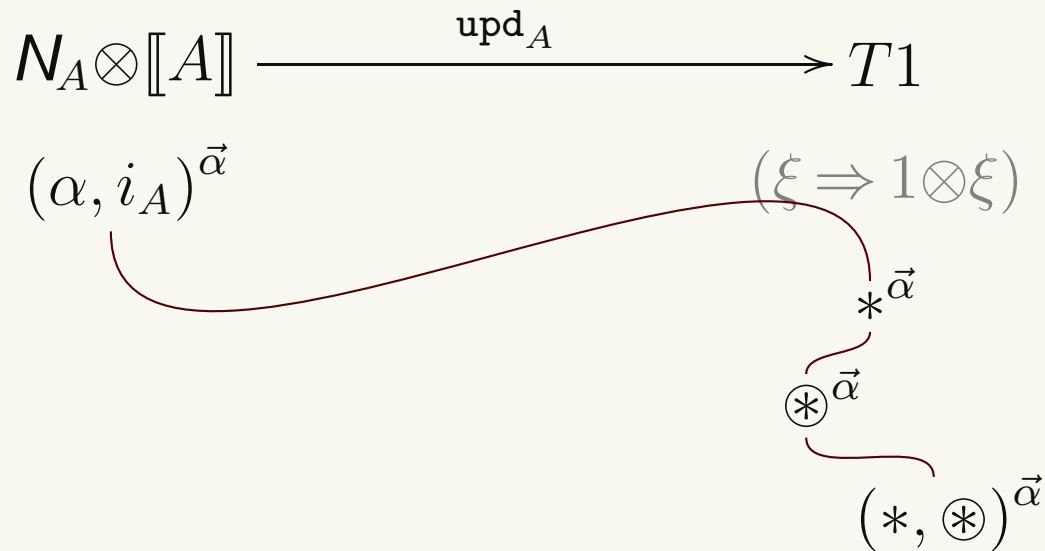
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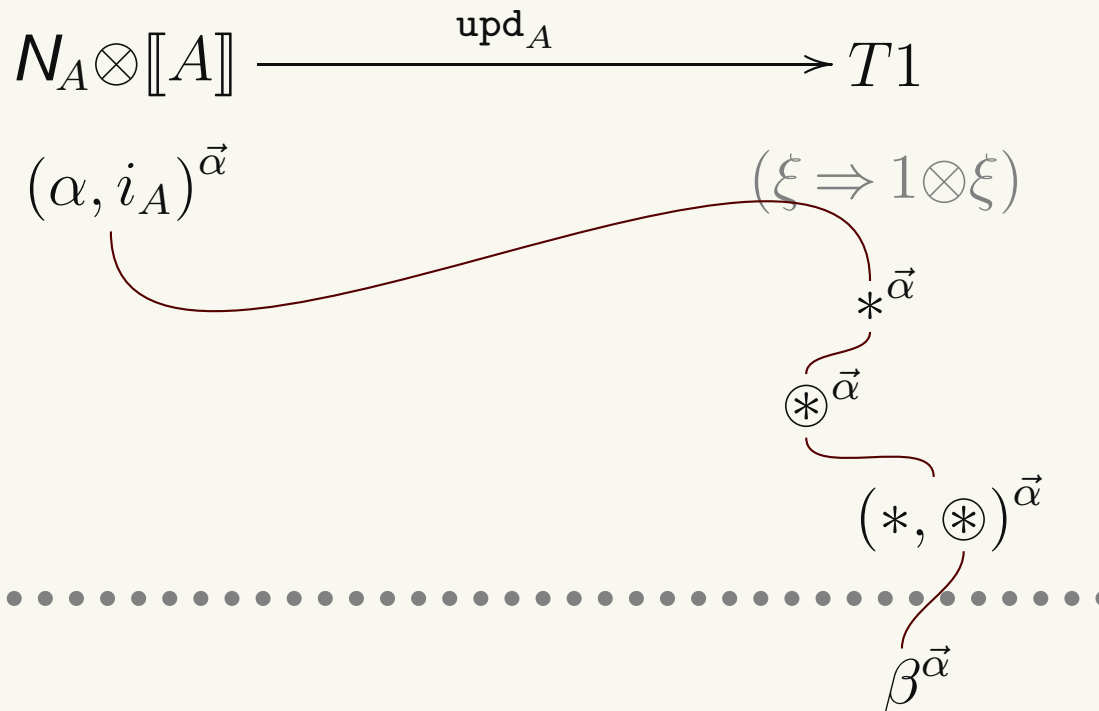


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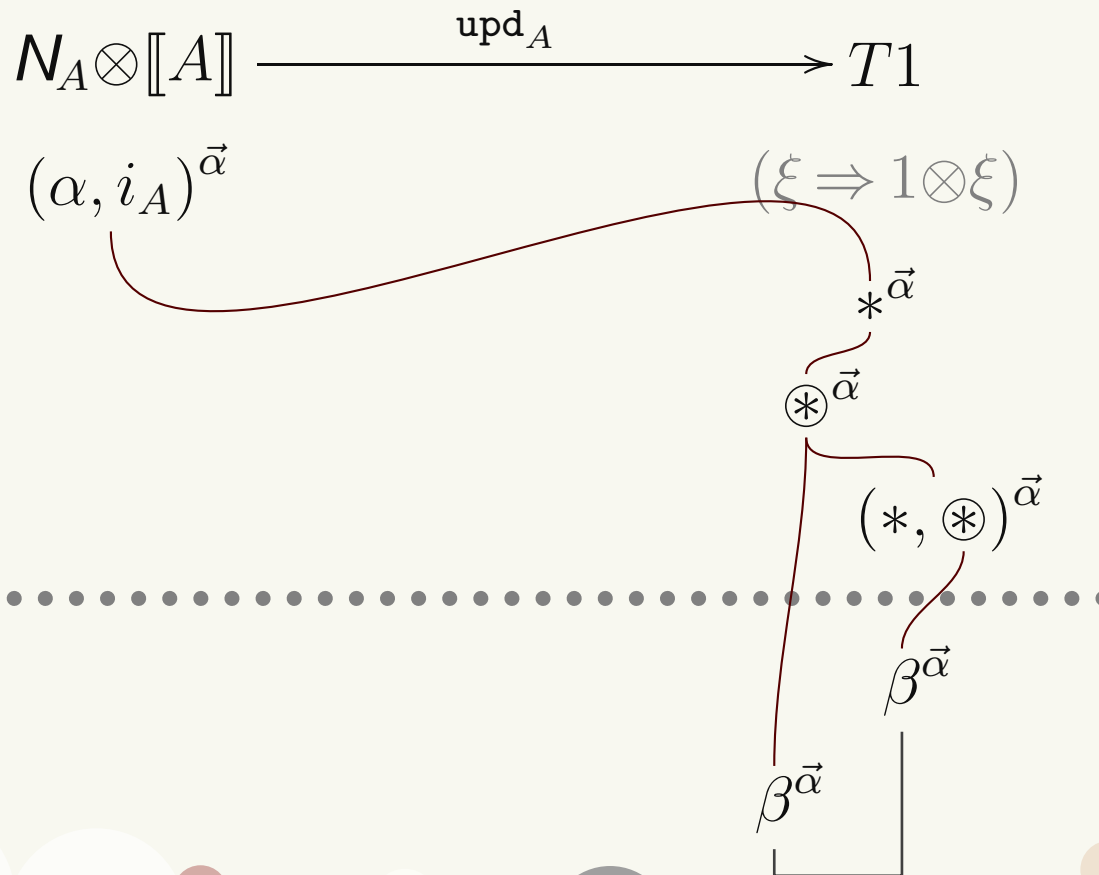


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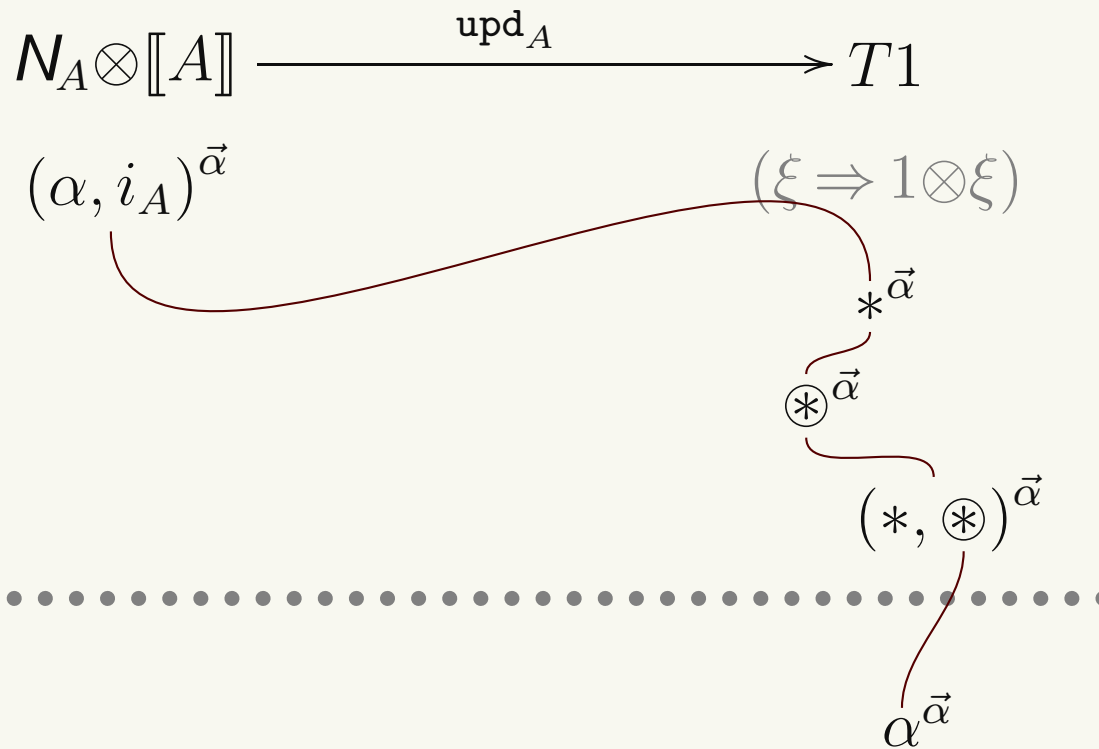


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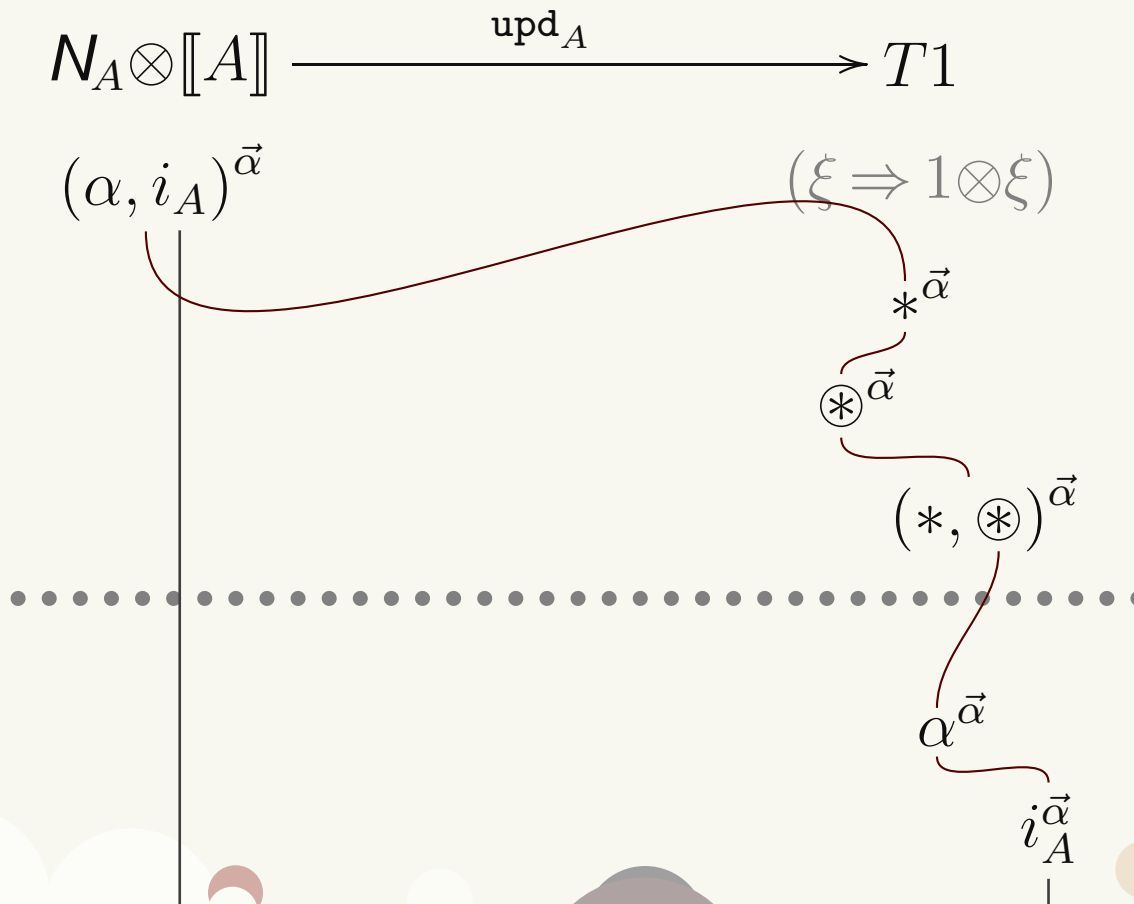


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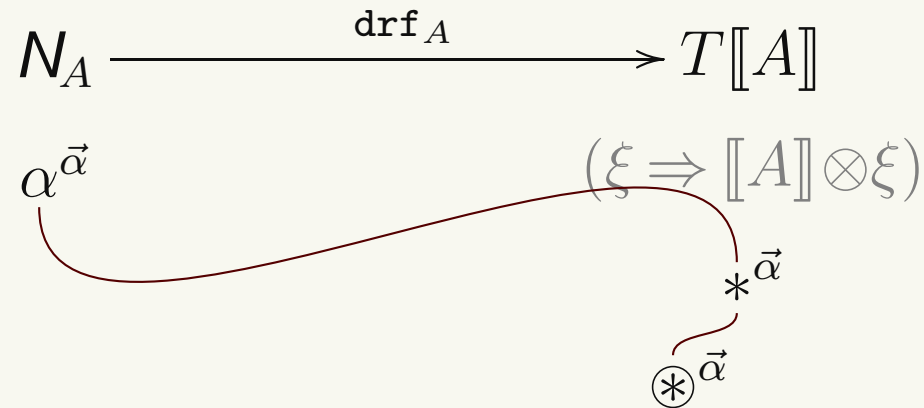
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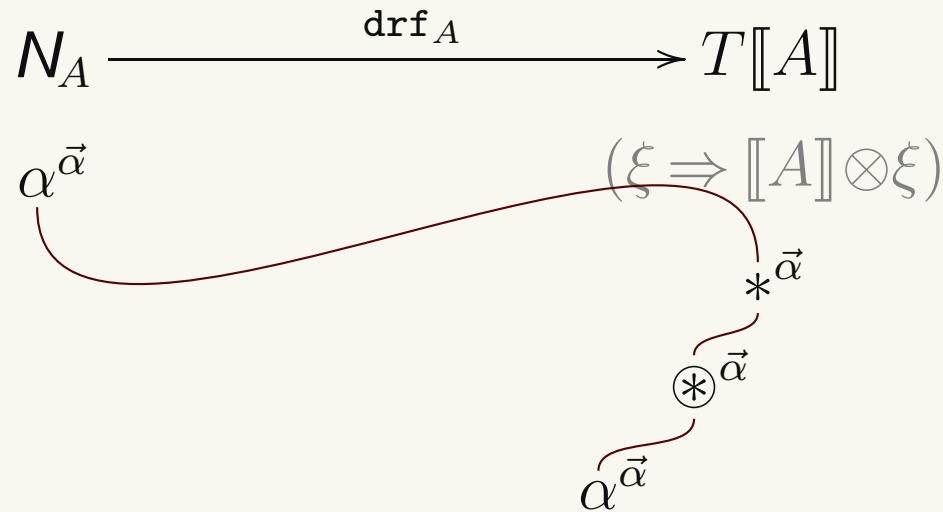
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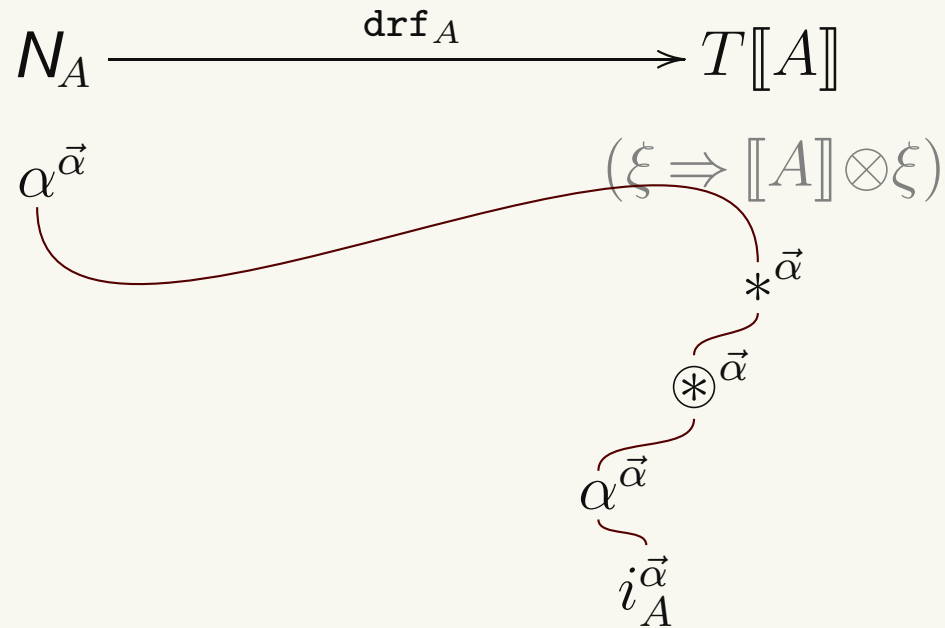
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When Opponent asks the value of some name, Player is free to evade answering and play elsewhere.

Tidy strategies

We therefore restrict strategies by imposing *tidiness conditions*, obtaining thus *tidy strategies*.

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An $\vec{\alpha}$ -strategy σ is *tidy* if whenever odd-length $[s] \in \sigma$ then:

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In particular, if $\alpha \# \ulcorner s \urcorner^-$ then the latter case holds.

(TD2) If $[s\alpha^{\vec{\alpha}'}] \in \sigma$ with $\alpha^{\vec{\alpha}'}$ a store-Q then $\alpha^{\vec{\alpha}'}$ is justified by last O-store-H in $\ulcorner s \urcorner^-$.

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Let $\mathcal{T}^{\vec{\alpha}}$ be the subcategory of $\mathcal{V}_t^{\vec{\alpha}}$ with objects $\llbracket A \rrbracket$
and arrows tidy strategies

\mathcal{T} is a FA model

All relevant structure passes from $\mathcal{V}_t^{\vec{\alpha}}$ to $\mathcal{T}^{\vec{\alpha}}$.
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We call an $\vec{\alpha}$ -strategy $\sigma : 1 \rightarrow T\mathbb{N}$ *observable* iff, for some $\vec{\beta}$,

$$[*^{\vec{\alpha}} *^{\vec{\alpha}} \circledast^{\vec{\alpha}}(0, \circledast)^{\vec{\alpha}\vec{\beta}}] \in \sigma$$

and define the *intrinsic preorder* $\lesssim^{\vec{\alpha}} \subseteq \mathcal{T}^{\vec{\alpha}}(A, TB)$ around it.

$$\llbracket M \rrbracket \lesssim \llbracket N \rrbracket \iff M \lesssim N$$

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